**Lesson 1: Learning Transportation Network**

**Introduction with the Tempe ASU Network**

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**Data set:**

<https://github.com/xzhou99/traffic-engineering-and-analysis/tree/master/lesson_1_learning_NeXTA_GMNS>

**Learning Objectives:**

1. Understand how to view/edit network attributes in NeXTA (4 problems)
2. Understand the user interface of NEXTA
3. Understand node and link files in GMNS format

## 1.1. Background introduction

The City of Tempe will soon start a construction project Along S Rural Road around the ASU campus. In order to complete this project, Rural Road must be partially closed (from 2 lanes in each direction to 1 lane in each direction) to create a safe work zone for the repair crews.

You (and an optional partner) have been tasked with creating a network model to evaluate the travel impacts (congestion, delay, etc.) associated with partially closing Rural Road.

### What is AMS?

As stated in FHWA website, <https://cms7.fhwa.dot.gov/research/operations/analysis-modeling-simulation/analysis-modeling-simulation-overview>, FHWA and its State and local agency partners have relied on analysis, modeling, and simulation (AMS) to support investment decisions for the transportation system. As the transportation system environment grows in complexity, increasing pressure is placed on agencies to identify more innovative and efficient solutions to a wide range of issues. These solutions include leveraging emerging technologies, data sources, and alternative (non-traditional) strategies. AMS tools will continue to play a critical role in evaluating these solutions.

### What is NEXTA?

In general, the software suite of NeXTA aims to:

(1) Provide an open-source code base to enable transportation researchers and software developers to expand its range of capabilities to various traffic management application.

(2) Present results to other users by visualizing time-varying traffic flow dynamics and traveler route choice behavior in an integrated environment.

(3) Provide a free, educational tool for students to understand the complex decision-making process in transportation planning and optimization processes.

## 1.2 Understand how to view/edit network attributes in NeXTA

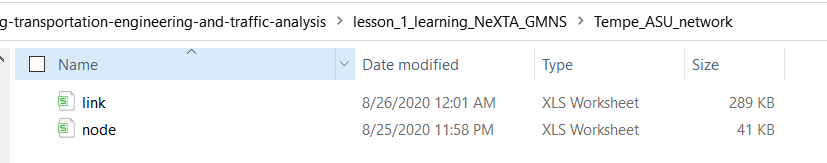
# Step 1: Download and Open NeXTA, Open the Tempe ASU Network

Before going into too much detail, first makes sure you’re using the most up-to-date version of NeXTA, and open the Tempe ASU network.

**Step 1.3:** Open the Tempe ASU Network in NeXTA

In NeXTA, go to File -> Open Traffic Network Project

In the Lesson 1, go to the Tempe\_ASU\_network folder, select the **node.csv** file, and click **Open**



NeXTA will open the network, and display the **File Loading Status window**. The File Loading Status window displays information about the network currently open in NeXTA, including information about the number of links, nodes, and zones/activity locations in the network. This window can also be accessed by going to **File -> Check Data Loading Status**.

**Problem 1:** How many nodes are in the Tempe ASU network? How many links are in the Tempe ASU network?

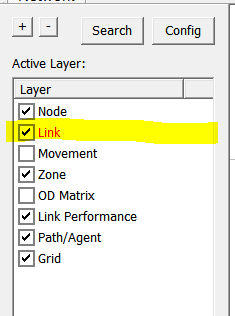
**Step 2: Viewing/Editing Network Attributes in NeXTA**

Network objects primarily consist of links, nodes, and zones. A driver starts and ends their trip at a zone, traveling along road segments (links) between the origin and destination. Links are connected together at nodes, where a node may represent an intersection or a simple connection between two road segments.

Since vehicles only travel along links, passing nodes between their origin and destination, trip details (such as travel time, distance, speed, etc.) are heavily dependent upon link and node attributes. The most important link attributes are typically link length, speed limit, number of lanes, and capacity. Since nodes typically represent intersections, their important attributes typically include node control type (signalized intersection, stop-controlled intersection, no control, etc.) and traffic signal-related attributes.

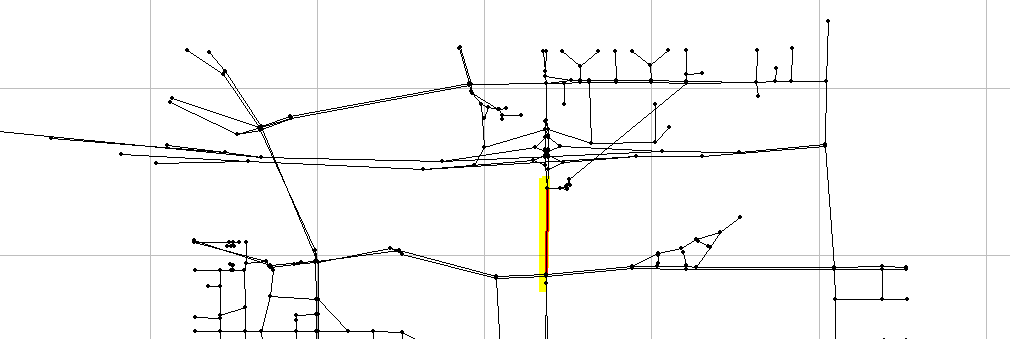
This section will quickly explain how to view and edit these network object attributes.

**Step 2.1:** To quickly view most link or node attributes, simply select a link or node using the Select Object tool, and look at the attributes in the GIS Layer Panel in the bottom right corner of the screen.

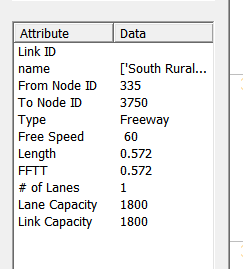


Select link layer as highlighted above.

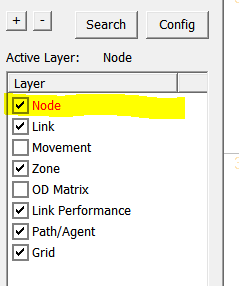
Select a link along Rural Road as shown below,



Check the Link Attribute display on the left hand size as shown below.

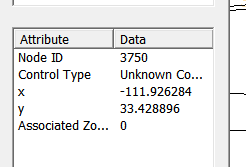


One can now select the node layer in the GIS Layer Panel,

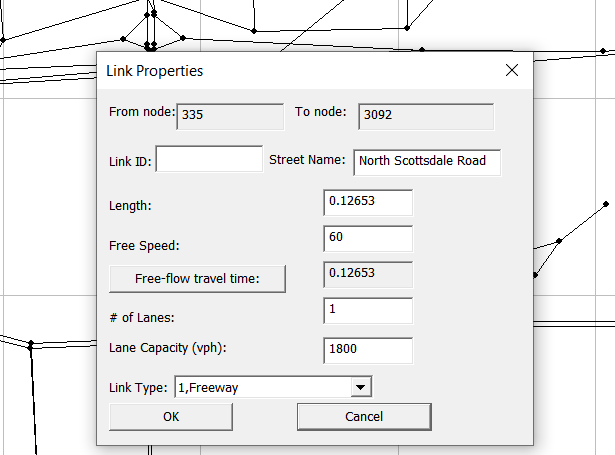


Select a node close to ASU campus,

Check the Node Attribute display on the left-hand size as shown below.



Alternatively, after selecting the link or node, **right-click** near the object and select either Edit Link Properties or Node Properties. Selecting Edit Link Properties opens the Link Properties dialog box, shown below. These dialog boxes offer the ability to edit individual link and node attributes quickly and easily - simply replace the text/values in the appropriate field, select OK, and click the Save button  on the Tool Bar to save your changes to the network.



**Problem 2:** In the current data set, not all the data have been fully updated and the information in the above dialog should be corrected in a later study.

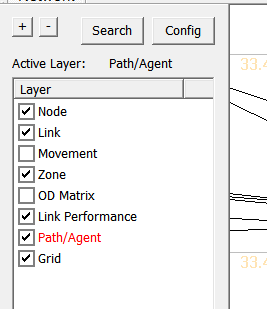
What is the current free-flow speed value along Rural Road? How many lanes are present along Rural Road in the model? What is the link type in the current model? What are the correct values in the real-world conditions?

**Problem 3:** What is link capacity? How is it different from lane capacity?

**Step 3: Find short paths and use path analysis tool in NeXTA**

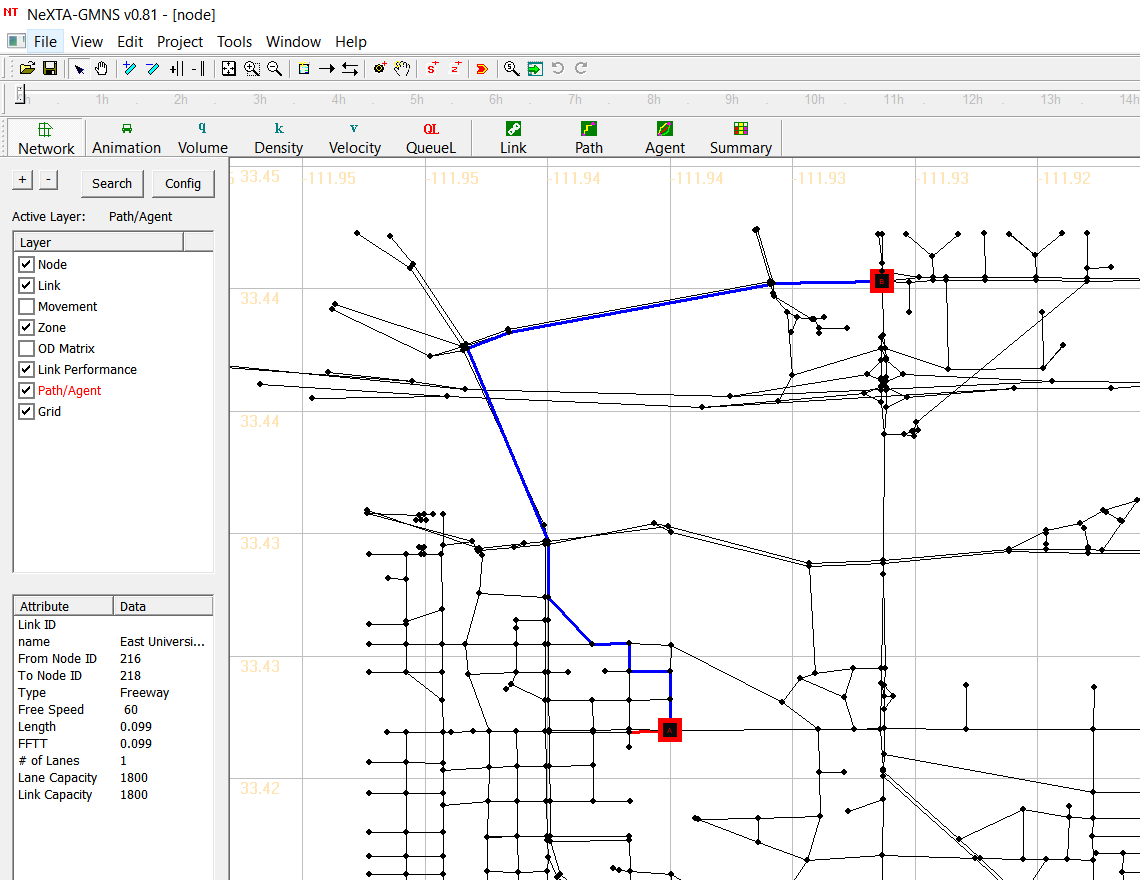
The Path Analysis Tool is enabled by using the  button or going to MOE > Path List Dialog, which is used to view link attributes and path travel time statistics.

To use the tool, a path must first be selecting in the path layer as shown below.



As a recap, this is accomplished by right-clicking the mouse at the origin node for the path, selecting “Direction from Here”, and then right-clicking again at the destination, selecting “Direction to Here”. The path is chosen automatically based on the shortest path between the two points.

Selecting the  button opens the Path Information window, as shown in the example below. Similar to the Link Information window, this tool shows link attributes for the links in the path.

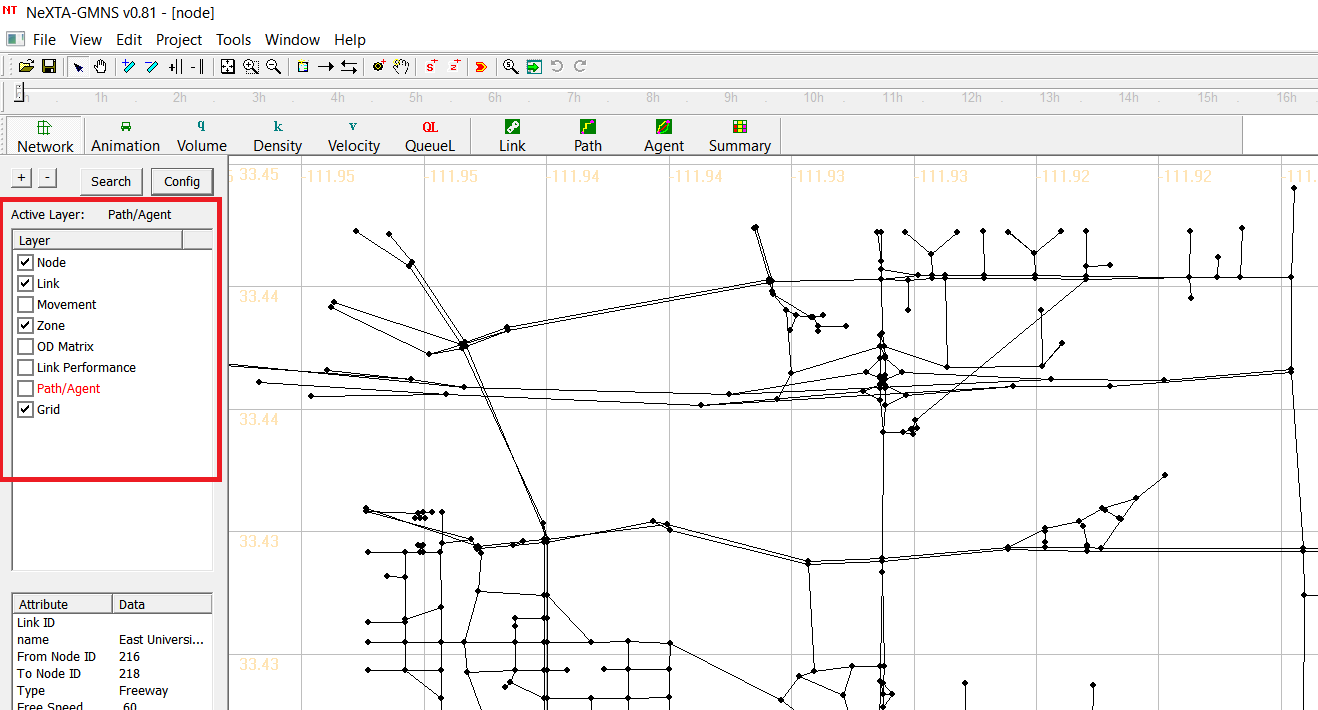


**Problem 4:** Select node 218 as the origin, and node 77 as the destination, find the path, and report the number of links and distance along this path. Try to find the same path using the Google Maps. To display the street names, you can go to the next section of **layer text label** to learn how to display names of links.

## 1.3. Understand user interfaces & basic controls of NeXTA

### Layer Control Panel

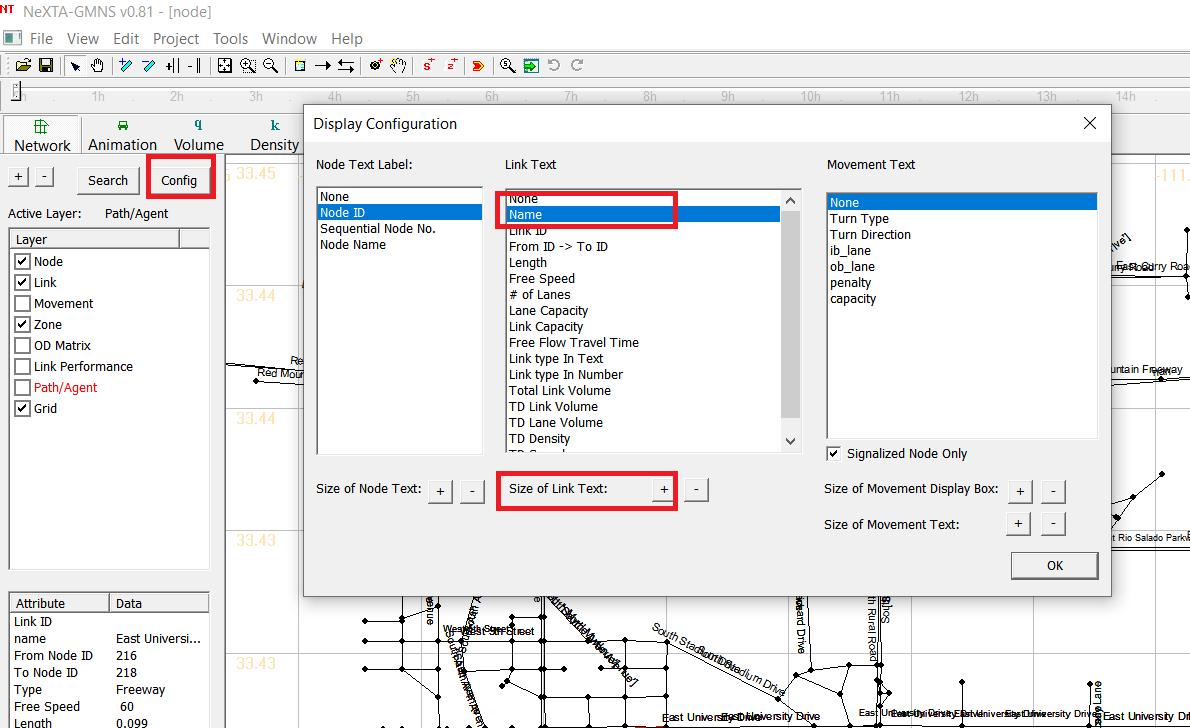
NeXTA’s user interface uses layer controls which are similar to those used in common GIS software applications to manage which network object types are displayed/selected.



The list of layers at the left side of the screen, highlighted in the figure above, is used to control what is visible in the display. The panel display controls the Node, Link, Movement, Zone, OD Matrix, Link Performance, Path/Agent, Grid. Each layer refers to a different type of network data, which is stored in the network input/output files in the project folder.

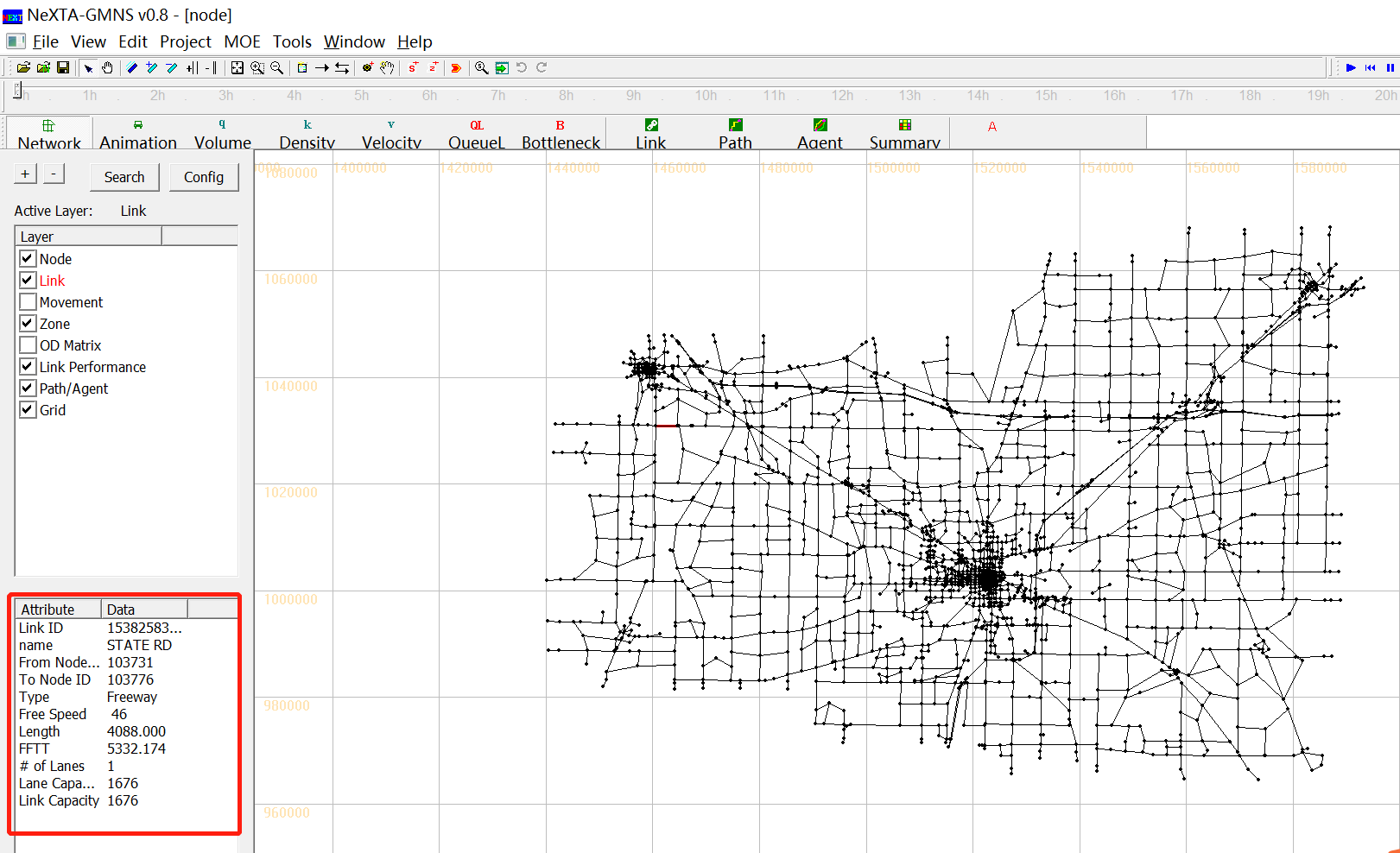
**The box alongside each layer’s text label** is used to control the layer’s visibility. An empty box indicates that the layer is not visible, and a check mark in the box indicates that the layer is visible (if data is available for display). In some cases, after turning a layer on or off, the user may need to click the layer’s text label to refresh the display for that specific layer.

**The layer text label** is used to control which objects can be selected in the network. In particular, the selectable layers are limited to the layers such as Node, Link, Movement, Zone and OD Matrix. With the layer turned on (enabled), left-clicking on the layer text label enables selection using the Select Object tool. The text label is highlighted in red text after selection, indicating which network object type can be selected using the Select Object tool. Please see more detail illustration for examples for using this functionality.

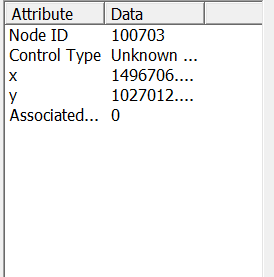
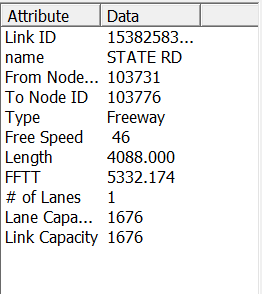


### Attribute Data Display Panel

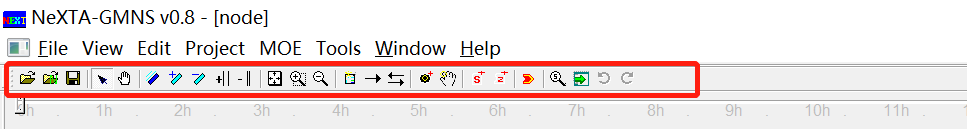
The lower half of the panel at the left side of the screen shows attribute data for a selected object, as shown in the figure below. The information displayed in this section of the panel is dependent upon the selected network object type.



Node attribute data displayed in the panel includes the node ID number, control type, geographic coordinates, and associated zone ID number (=corresponding zone number, if a node is an activity location; =0, otherwise) for the selected node. Link attribute data displayed in the panel includes the link ID number, link name, starting node ID number, ending node ID number, link type, speed limit, length, free-flow travel time, number of lanes, lane capacity and link capacity for the selected link. An example is shown in the figure below with link attribute data.

## Management Toolbar



### Basic Management Tools

|  |  |  |
| --- | --- | --- |
| **Icon** | **Name** | **Function** |
|  | Open Project |  |
|  | Open New Project |  |
|  | Save Project | Save network to given path/file name |
|  | Select Object | Select a node/link/zone |
|  | Move Network |  |
|  | Switch Link Bar/Line Display Mode |  |
|  | Increase Link Bandwidth |  |
|  | Decrease Link Bandwidth |  |
|  | Increase Link Offset |  |
|  | Decrease Link Offset |  |
|  | Show Network | Show entire network |
|  | Zoom In |  |
|  | Zoom Out |  |
|  | Search Node/ Link/Path/Vehicle | Opens a dialog box which enables search functionality in NeXTA. Search by node number to find nodes, links (from node and to node notation), paths (from node and to node notation, using shortest path), and vehicle number (when simulations results are available). |

### 

### Network Editing Tools

|  |  |  |
| --- | --- | --- |
| **Icon** | **Name** | **Function** |
|  | Set Default Link Type | Opens a dialog box displaying the default link properties for different link types. The user may select and edit the default link properties so that all new links created afterward are assigned those changes. |
|  | Add New One-Way Links | Create a new one-way, directional link between two nodes. |
|  | Add New Two-Way Links | Create two one-way, directional links between two nodes. |
|  | Add New Node | Create a new node to which links can be attached. |
|  | Move Node Position |  |
|  | Create Subarea for subarea Analysis | Create a subarea boundary which is used to perform a subarea cut (see Subarea Analysis for more details). |
|  | Create New Zone | Create a new zone |

## Viewing Modes



Two different viewing modes are available in NeXTA - Network View mode and Animation View mode. The default Network View mode is used to display Measures of Effectiveness (MOEs) and the network geometry, while the Animation View is used to show individual vehicles moving in the network during simulation. The user can use the and  buttons on the MOE Toolbar to control which view is used.

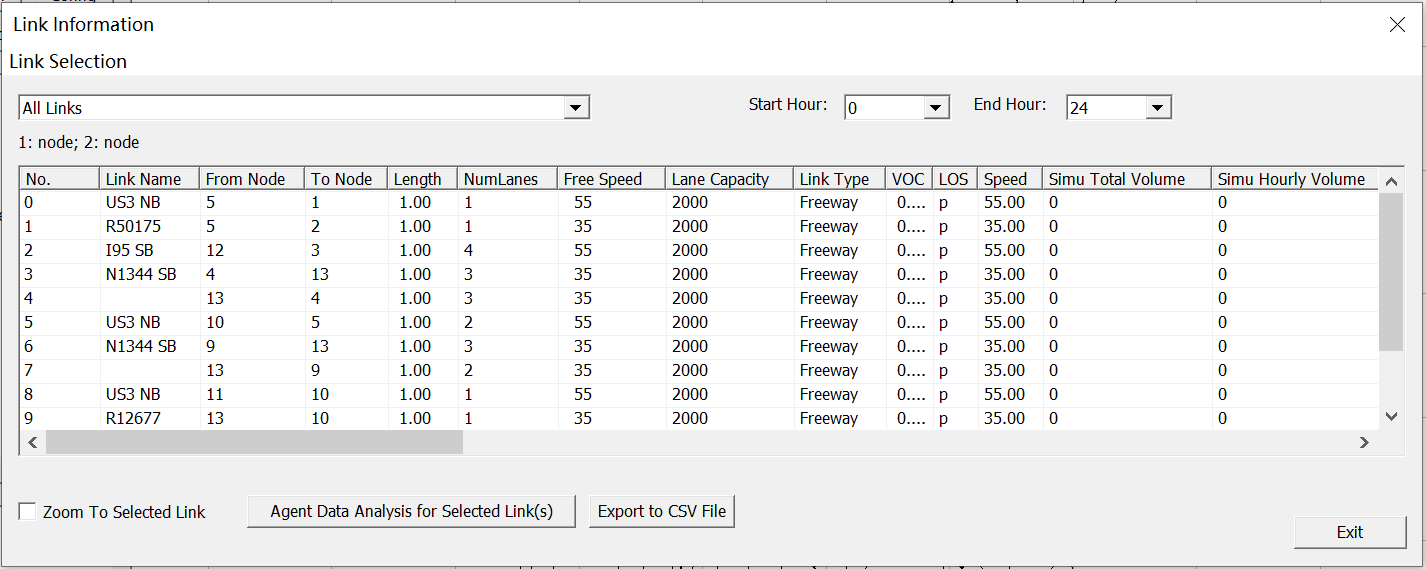
## Detailed Analytical Tools



In addition to the previously-described visualization tools, the Link, Path, Vehicle, and Summary analytical tools are available for more detailed analyses. These features may be accessed through the highlighted buttons shown below on the MOE Toolbar. Each visualization feature is explained in different sections below.

### Link Analysis Tool

Selecting the  button, or going to MOE > Link List Dialog, opening the Link Information window (as shown below), which is used to view link attributes and MOEs. Selecting a row with the mouse also selects the link in the network, allowing the user to quickly find specific links. The Link Zoom toggle button at the bottom left side of the window centers the network view window at the selected row after a row is selected. Each column of data can be used to sort the list, allowing the user to more quickly find links with specific attributes or which meet certain criteria. The “Vehicle Data Analysis for Selected Link(s)” button at the bottom of the window offers vehicle analysis data for selected links. The “Export to CSV File” button at the bottom of the window helps users export link information and MOEs to CSV file.



Additionally, the Link Selection menu at the top left side of the window offers options for filtering the rows by link type. Filtering options are available for displaying only Selected links, links within Subarea, Freeway, Highway, Ramp, Arterial, Connector links and Non-Connector links. The Start/End Hour Selection menu at the top right side of the window offer options for analysis period.

## 1.4. Understand node and link files in GMNS format

### What is GMNS?

General Travel Network Format Specification is a product of Zephyr Foundation, which aims to advance the field through flexible and efficient support, education, guidance, encouragement, and incubation.

Further Details in <https://zephyrtransport.org/projects/2-network-standard-and-tools/>

This section describes all input and output files associated with NeXTA package. All GMNS data files are in CSV format. Each input/output file includes descriptions for required variable names, followed by a short description of their type, purpose, function, interaction with other variables, and the use cases in which the variable is required/not required.

**Network data structure** defines the basic node-link structure, along with attributes for each link and node. Additionally, nodes are related to movement, which can be used to disaggregate trips from nodes to nodes.

Below is a short list of key features for GMNS data files and simple AMS data structure. In the current lesson, we only need to cover node.csv and link.csv, and the other files will be examined in the future.

|  |  |
| --- | --- |
| **File Name** | |
| A: GMMS Network Files | A1: node.csv |
| A2: link.csv |
| A3: movement.csv |
| B: AMS Output | B1: [link\_performance.csv](https://docs.google.com/spreadsheets/d/1gToOECJqT2T2rDpS6YSPRXZvz-xi4iN2iV32nrjK-AQ/edit" \l "gid=2142282830) |
| B2: [agent.csv](https://docs.google.com/spreadsheets/d/1Jrmq3tlV22qrwJb4tzHivMio04DNHZwHqdlJOcE_oIc/edit" \l "gid=689476001) |

### High-level introductions:

* A generic network used for GMNS readable by NeXTA includes a set of three layers: node, link and movement.
* The specific file names are node.csv, road\_link.csv, and movement.csv.
* A link is defined using upstream node and downstream node ids, with essential attributes such as length, free\_speed, lanes and capacity, typically required for static traffic assignment and mesoscopic traffic assignment.
* The movement file contains the individual’s movement from nodes to nodes.
* The node and link layers can use arbitrary coordinate system, but a WKT (lon/lat) coordinate system is preferred.
* A user can also manually create a new network from the scratch by using a click-and-draw method based on a background image file.

#### 1. node.csv

|  |  |  |
| --- | --- | --- |
| **Field Name** | **Description** | **Sample Value** |
| name | Optional for visualization only | Main street @ Highland Dr. |
| node\_id | Node identification number | 1001 |
| ctrl\_type | Intersection control type | 5 |
| node\_type | Optional text label for visualization and identifies of node | 1 |
| x\_coord | Longitude or horizontal coordinate in any arbitrary geographic coordinate system. | 100 |
| y\_coord | Latitude or vertical coordinate horizontal coordinate in any arbitrary geographic coordinate system | 200 |
| geometry | Text string used to describe node location <https://en.wikipedia.org/wiki/Well-known_text_representation_of_geometry> | POINT (30 10) |

#### 2. link.csv

|  |  |  |
| --- | --- | --- |
| **Field Name** | **Description** | **Sample Values** |
| Name | Optional for visualization purposes | Main Street |
| link\_id | Link identification number of the road | 101 |
| from\_node\_id | Upstream node number of the link, must already defined in input\_node.csv | 2 |
| to\_node\_id | Downstream node number of the link, must already defined in input\_node.csv | 3 |
| link\_type | Optional text label for visualization and data checking purposes | 1 |
| length | The length of the link (between end nodes), measured in units of miles. | 1.0 |
| lanes | The number of lanes on the link | 2 |
| free\_speed | Free-flow speed on defined link . Suggested Unit: mph or kmph | 20 |
| capacity | The number of vehicles per hour per lane. | 1500 |
| geometry | Text string used to describe link shape and location (typically in WKT geographic coordinate system). The initial value can be empty, and NeXTA will generate the text string based on the coordinates of upstream and downstream nodes. | LINESTRING (30 10, 10 30, 40 40) |